

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L2	329	program\$4 near4 (robotic adj2 arm)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L3	3	program\$4 near4 (robotic adj2 arm) and toy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L4	1264	toy near3 robot	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L5	268	(toy near3 robot) and program\$3 and input\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L6	7	"657032".ap.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L7	803	(robot\$2 with input with movement)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L8	399	(robot\$2 with input with movement) and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L9	169	(robot\$2 with input with movement) and memory and ((start\$3 or initial or final or end\$3) near3 (position))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10

EAST Search History

L10	30	toy same robot same (reproduc\$3 or repeat\$3 or learn\$3) same (motion or movement)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L11	1215	robot with learn\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L12	142	(robot with learn\$3) and toy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L13	7	(robot with learn\$3) and toy and (manual\$3 with input\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L14	308	901/3.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L15	114	901/4.ccls.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L16	329	program\$4 near4 (robotic adj2 arm)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L17	1264	toy near3 robot	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10

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L18	803	(robot\$2 with input with movement)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L19	399	(robot\$2 with input with movement) and memory	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L20	142	(robot with learn\$3) and toy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L21	3	program\$4 near4 (robotic adj2 arm) and toy	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L22	7	"657032".ap.	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L23	30	toy same robot same (reproduc\$3 or repeat\$3 or learn\$3) same (motion or movement)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L24	7	(robot with learn\$3) and toy and (manual\$3 with input\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L25	268	(toy near3 robot) and program\$3 and input\$4	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10

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L26	169	(robot\$2 with input with movement) and memory and ((start\$3 or initial or final or end\$3) near3 (position))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L27	1215	robot with learn\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L28	134	(electronic with (dart near2 board))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L29	0	(electronic with (dart near2 board)) and insult\$3	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L30	0	(electronic with (dart near2 board)) and nervous	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L31	1	(electronic with (dart near2 board)) and (insult\$3 or heckl\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L32	1	(electronic with (dart near2 board)) and (insult\$3 or heckl\$3 or taunt\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L33	749	(game) and (insult\$3 or heckl\$3 or taunt\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10

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L34	5	(game) and darts and (insult\$3 or heckl\$3 or taunt\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L35	116	(video adj2 game) and (insult\$3 or heckl\$3 or taunt\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L36	55	(video adj2 game) and (insult\$3 or heckl\$3 or taunt\$3)	USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L37	1	"463"/\$.ccls. and ((insult\$3 or heckl\$3 or taunt\$3) with (audio or audible))	USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L38	7	game and ((insult\$3 or heckl\$3 or taunt\$3) with (audio or audible))	USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L39	1	("6283872").URPN.	USPAT	OR	OFF	2007/05/13 21:10
L40	15	("0709802" "2421279" "3117785" "3456950" "4488373" "4832339" "5009418" "5135221" "5193819" "5288069" "5679047").PN.	US-PGPUB; USPAT; USOCR	OR	OFF	2007/05/13 21:10
L41	1	"20030055533".PN.	US-PGPUB	OR	OFF	2007/05/13 21:10
L42	230	robot\$2 with (manual\$2 near4 (teach\$3 or learn\$3))	USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L43	301	robot\$2 with (manual\$2 near4 (teach\$3 or learn\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L44	1	"20020107591".PN.	US-PGPUB	OR	OFF	2007/05/13 21:10

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L45	573	robot\$2 and (manual\$2 near4 (teach\$3 or learn\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L46	8278	robot\$2 and (manual\$2 near4 teach\$3 or learn\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L47	7	(robot with learn\$3) and toy and (manual\$3 with input\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L48	7	(robot with learn\$3) and toy and (manual\$3 with input\$3)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L49	30	toy same robot same (reproduc\$3 or repeat\$3 or learn\$3) same (motion or movement)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L50	1	"20020107591".PN.	US-PGPUB	OR	OFF	2007/05/13 21:10
L51	169	(robot\$2 with input with movement) and memory and ((start\$3 or initial or final or end\$3) near3 (position))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L52	573	robot\$2 and (manual\$2 near4 (teach\$3 or learn\$3))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10
L53	329	program\$4 near4 (robotic adj2 arm)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/05/13 21:10